

# Clarinet And Piano Duets

F Rizvi

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by transforming each of the vectors of the standard basis by  $t$  then inserting the result into the columns of a matrix in other words for example the function is a linear transformation  
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 web in linear algebra a rotation matrix is a transformation matrix that is used to perform a rotation in euclidean space for example using the convention below the matrix rotates points in the  $xy$  plane counterclockwise through an angle  $\theta$  about the origin of a two dimensional cartesian coordinate system  
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 web matrices as transformations of the plane google classroom about transcript we can think of a  $2 \times 2$  matrix as describing a special kind of transformation of the plane called linear transformation by telling us where the vectors  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  are mapped to we can figure out where any other vector is mapped to created by sal khan questions  
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encode transformations such as  
rotation and reflection but not  
translation for that you need to add a  
fourth element and represent your  
vectors in terms of homogenous  
coordinates it is possible to use non  
square matrices for certain purposes  
but if you want to be able to compose  
them in any order they should be  
square

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that transforms one vector into another  
vector by the process of matrix  
multiplication the transformation  
matrix alters the cartesian system and

maps the coordinates of the vector to  
the new coordinates

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transformations about this unit  
matrices can be used to perform a wide  
variety of transformations on data  
which makes them powerful tools in  
many real world applications for  
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computer graphics to rotate scale and  
translate images and vectors

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web orthogonality of the transformation  
matrix  $q$  as in the two dimensional case  
the transformation matrix is orthogonal  
 $q^T q = I$  this follows from 1 5 11 1 5 13  
example consider a cartesian  
coordinate system with base vectors  $e_i$   
a coordinate transformation is carried  
out with the new basis given by 3 3 2 3  
3 1 2 3 3 1 3 2

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web coordinates of  $v$  the standard  
coordinates are  $v_3$  are the  $b_1 b_2$  are

assumed if no other basis is speci ed  
this means  $v = v_1 e_1 + v_2 e_2 + v_3 e_3$  if  $b_1, b_2$   
 $v$  is a basis of  $\mathbb{R}^n$  then the matrix  $S$   
which contains the vectors  $v_k$  as  
column vectors is called the coordinate  
change matrix

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web the vector  $b$  is parallel to  $a$  and  
points in the same direction if  $\alpha > 0$  for  $\alpha < 0$  the vector  $b$  is parallel to but points  
in the opposite direction antiparallel if  
we multiply an arbitrary vector  $a$  by the  
inverse of its magnitude  $1/|a|$  we obtain a  
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transformation  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  that assigns to a vector  $\mathbf{x}$  the closest vector on horizontal axis as illustrated in figure 2.6.20 this transformation is called the projection onto the horizontal axis

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web and now that we know what  $d$  is we can now solve for  $a$  we can now solve for the transformation matrix with respect to the standard basis so to do that we have to figure out  $c$  and  $c$  inverse so  $c$  remember  $c$  is just the change of basis matrix and all that is is the basis vectors it's just a matrix with the basis vectors in the column  
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web a translation by a nonzero vector is not a linear map because linear maps must send the zero vector to the zero vector however translations are very useful in performing coordinate transformations i'll introduce the following terminology for the composite of a linear transformation and a translation definition let  $a$  be a real matrix

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web any vector  $\mathbf{v}$  represented in  $b$  can be transformed to a representation in  $c$  as follows under the transformation of basis notice that the superscript on the transformation matrix  $m$  and the subscript on the coordinate vector  $\mathbf{v}$  are

the same and seemingly cancel leaving the remaining subscript

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